Chapter I: Introduction §1.2 Solving Some DE §1.3: Classification of DEs

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#### Equations from §1.1

We recall the equations discussed in  $\S1.1$ .

Falling Object Models:

$$m\frac{dv}{dt} = mg - \gamma v \tag{1}$$

$$10\frac{dv}{dt} = 98 - 2v$$
 or  $\frac{dv}{dt} = 9.8 - .2v$  (2)

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Population Growth Model:

$$\frac{dp}{dt} = rp \tag{3}$$

$$\frac{dp}{dt} = .5p - 450 \tag{4}$$

General First Order Equations:

$$\frac{dy}{dt} = f(t, y) \quad \text{where } f \text{ is a function of } t, y. \tag{5}$$

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The equations in §1.1 have been fairly simple, in the sense:

- ► All the DEs are of the form (5):  $\frac{dy}{dt} = f(t, y)$ . It involves only first derivative; and no higher order derivatives.
- For these DEs (1, 2, 3), the right side f(t, y) are linear.
- Solving such DEs (5), mainly, involves nothing more than revisiting antiderivatives.

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# Solving the Growth Model

We solve the population growth model (4)

$$\frac{dp}{dt} = .5p - 450 \implies \frac{dp}{.5p - 450} = dt$$
 (6)

•  $\int \frac{dp}{.5p-450} = \int dt + C$ , where C is an arbitrary constant.

• Substituting u = .5p - 450 we get

$$\frac{du}{u} = .5 \int dt + C \quad Or \quad \ln|u| = .5t + C$$

 $|.5p - 450| = e^{.5t + C} = ce^{.5t}$  Or  $p = 900 + ce^{.5t}$ 

wher  $c := \pm e^{C} > 0$  is an arbitrary constant.

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## Initial Value

- p = 900 + ce<sup>.5t</sup> is a solution of (6), for all values of c.
   This would be called the General solution
- In the absence of additional information, we cannot determine the value of c.
- Such extra information is provided, often, by giving the population size p(t<sub>0</sub>) at a particular time t<sub>0</sub>. For example, it may be given that p(0) = 1000. Such information, is called an initial value.

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• In case, 
$$p(0) = 1000$$
, we have

$$1000 = p(0) = 900 + c, \quad c = 100$$

Finally, our particular solution is  $p = 900 + 100e^{.5t}$ 

In the next frame, compare the direction fields of the DE (4), with this solution p = 900 + 100e<sup>.5t</sup>.

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#### Solving such general equations

More generally, consider the initial value problem:

$$\begin{cases} \frac{dy}{dt} &= ay - b\\ y(0) &= y_0 \end{cases} \quad a, b \text{ are constants, and} \quad (7)$$

 $y_0$  is (an) initial value of y, at time t = 0.

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#### (Trivial cases):

• If a = 0 then the equation is rewritten as

$$\begin{cases} \frac{dy}{dt} = -b \\ y(0) = y_0 \end{cases}$$
 Solution : exercise

If ay − b = 0 then, y = y(t) = b/a and there is nothing to solve. We have

$$\begin{cases} \frac{dy}{dt} = 0\\ y(0) = y_0 \end{cases}$$
 Solution : (Answer :  $y = y_0 = b/a$ )

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#### (The Non-Trivial case):

$$\begin{cases} \frac{dy}{dt} = ay - b \\ y(0) = y_0 \end{cases} \qquad a \neq 0, ay - b \neq 0 \qquad (8)$$

We proceed as in the growth model equation:

- We have  $\frac{dy}{ay-b} = dt$ . So,  $\int \frac{dy}{ay-b} = \int dt + C$ , where C is an arbitrary constant.
- ► So,

$$\int \frac{dy}{y - \frac{b}{a}} = a \int dt + C \Longrightarrow \ln \left| y - \frac{b}{a} \right| = at + C$$

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- ► Taking exponential: The general solution of (8) is:  $y - \frac{b}{a} = ce^t$  where  $c = \pm e^C$  is also arbitrary
- c = 0 corresponds to the equilibrium solution  $y = \frac{b}{a}$ .
- Using the initial value  $y(0) = y_0$ :  $y_0 \frac{b}{a} = c$
- ► So, the final solution of the initial value problem (8) is:  $y - \frac{b}{a} = [y_0 - \frac{b}{a}] e^{at}$ . Which is

$$y = \frac{b}{a} + \left[ y_0 - \frac{b}{a} \right] e^{at}$$
 (9)

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# Standard Examples

Following are some of the standard examples, available in the textbooks:

- Mass of decaying mass (usually radio). The Population Growth Model above, the growth or amortization of an interest paying account would be analogous.
- Motion of an ejected or falling body.
- Concentration of salt (or impurity) in a solution that is constantly diluted.

We discuss such examples subsequently.

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## Example 1: Decaying Mass

**Statement:** Let Q(t) denote the mass of some radio-active substance, at time t. It is known that such substances disintegrates at a rate proportional to the current mass Q(t). Write down a model, for this phenomenon.

- The rate of disintegration, at time t would be <sup>dQ</sup>/<sub>dt</sub>. According to the above stated model, <sup>dQ</sup>/<sub>dt</sub> is proportional to Q(t).
- ▶ So, the model is  $\frac{dQ}{dt} = -rQ(t)$ , for some constant r > 0.
- By (8) and solution 9, with b = 0, a = -r, we have

$$Q(t) = Q(0)e^{-rt}$$

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**Statement:** Now suppose initial mass is 1000 grams, which reduces to 900 grams in 10 hours. Compute *r*.

- ► We are also given Q(0) = 1000 gram and Q(10) = 900 grams (Unit of time used is "hours").
- So, we have

$$900 = 1000e^{-10r}. \quad r = -\frac{\ln(.9)}{10} = .0105$$

• So, 
$$Q(t) = 1000e^{-.0105t}$$

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# Example 2: Motion of a Falling Body

**Statement:** A missile has a vertical motion and horizontal motion. In this example, we only consider the vertical motion of such a missile. Suppose such a missile of mass 1000 kg, is projected and the vertical drag is proportional to square of the velocity. We formulate the model for vertical velocity.

- v(t) will denote the vertical of the missile, at time t.
- ► The model of the falling body DE (1) was modified, by changing model on drag. By the stated model, the drag= γv<sup>2</sup>.
- So, the new model DE is

$$m\frac{dv}{dt} = mg - \gamma v^2 \tag{10}$$

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▶ Recall  $g = 9.81 \text{ meter}/s^2$ . With m = 1000 kg. So, we have

$$\frac{dv}{dt} = 9.81 - \frac{1}{1000}\gamma v^2 \tag{11}$$

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Statement: Now suppose the vertical acceleration reduces to zero, when velocity v(t) = 100 meter/sec. Compute the drag constant  $\gamma$ .

• We have, acceleration  $\frac{dv}{dt} = 0$ , when v = 0. Substituting in (11),

$$0 = 9.81 - \frac{1}{1000}\gamma(100^2).$$

 $\blacktriangleright\,$  So,  $\gamma=$  .981 and the model is

$$\frac{dv}{dt} = 9.81 - \frac{.981}{1000}v^2 = \frac{.981}{1000}\left(10000 - v^2\right)$$

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► We separate variables (see §2.3):

$$\int \frac{dv}{v^2 - 10000} = -\frac{.981}{1000} \int dt + c \implies$$
$$\int \frac{1}{200} \left( \frac{1}{v - 100} - \frac{1}{v + 100} \right) dv = -\frac{.981}{1000} + c \Longrightarrow$$
$$\frac{1}{200} \ln \left| \frac{v - 100}{v + 100} \right| = -\frac{.981}{1000} + c \Longrightarrow$$

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$$\left| \frac{v - 100}{v + 100} \right| = Ce^{-.1962t} \quad \text{with} \quad C = e^{200c} > 0$$
  
So,  

$$\frac{v - 100}{v + 100} = Ce^{-.1962t} \quad \text{with} \quad -\infty < C < \infty$$

• Substituting v(0) = 0 we have C = -1

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So, the solution is given by

$$\frac{v-100}{v+100} = -e^{-.1962t} \Longrightarrow$$

$$v(t) = 100 - (v + 100)e^{-.1962t}$$

Next Level: Let h = h(t) denote the vertical distance of the missile, from the point of ejection, at time t. So,

$$\frac{dh}{dt} = v = v(t) = 100 - (v + 100)e^{-.1962t}$$

This equation can be solved to determine the height h(t), of the missile, at time t.

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#### Example 3: Concentration

**Statement:** A water reservoir contains  $10^6$  gallons of water. The water is not acceptable for human consumption, due the level of chemicals in the water. The concentration of this chemicals is .01 gm/gallon. Pure water is added to the pond at the rate of 1,000 gallons/h. The well mixed water drains out of the pond at the same rate . Model the total quantity of chemicals in the pond and determine the concentration of the chemicals after one year.

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#### Solution:

- Let Q(t) =quatity of the chemical in the pond, at time t.
- So,  $Q(0) = .01 * 10^6 = 10^4 \text{ gm}.$
- Part a): The rate of change

$$rac{dQ}{dt} = -1000 * rac{Q(t)}{10^6} = -rac{Q(t)}{10^3}$$

We can use the general solution solution (9) or rework it out. I will rework. We have

$$\int \frac{dQ}{Q} = -\int \frac{dt}{10^3} + c$$
 c is a constant.  
 $\ln Q(t) = \frac{t}{10^3} + c.$ 

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So,  $Q(t) = Ce^{-\frac{t}{10^3}}$   $C \ge 0$  is a constant Now,  $Q(0) = 10^4 \Longrightarrow 10^4 = C$ . So, the solution is  $Q(t) = 10^4 e^{-\frac{t}{10^3}}$ Finally, after one year, t = 365 \* 24 = 8760. So,  $Q(1 \text{ year}) = Q(8760) = 10^4 e^{-\frac{8760}{10^3}} = 10^4 e^{-8.760}$ 

So, the concentration is

$$= \frac{Q(1 \text{ year})}{10^6} = \frac{10^4 e^{-8.760}}{10^6} \text{ per gallon. This is near zero.}$$

#### §1.3 Classification based on no of ind. variables

Two broad classifications of DEs are as follows:

- When a DE involves only a single independent variable x (or t), then it is called an Ordinary DE (also called ODE). Chapter 2, 3 would be on ODE.
- ▶ When a DE involves more than one independent variables x<sub>1</sub>, x<sub>2</sub>,..., x<sub>n</sub>, then it is called a Partial DE (also called PDE). PDEs will not be covered in this course.

# Classification based on number of unknown variables

- There may only be one unknown dependent variable y, to be determined. As in linear algebra, only one DE (plus initial value) is needed to determine y.
- ► There may also be more than one unknown dependent variables y<sub>1</sub>, y<sub>2</sub>,..., y<sub>m</sub>, to be determined. As in linear algebra, a system of m (independent, in some sense) DE (plus initial values) are needed to determine y<sub>1</sub>, y<sub>2</sub>,..., y<sub>m</sub>. They will be called a System of DEs. We will consider such systems in chapter 7.

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#### Based on Order of derivatives

- DEs can be classified based on highest order of derivation present. We will cover
  - First order DE (Chapter 2)
  - Second order DE (Chapter 3)

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#### Linearity and non-linearity

An ODE of order n is called linear, if it looks like

$$a_0(t)rac{d^n y}{dt^n} + a_1(t)rac{d^{n-1} y}{dt^{n-1}} + \cdots + a_{n-1}(t)rac{dy}{dt} + a_n(t)y = g(t)$$

This is also written as:

$$a_0(t)y^{(n)} + a_1(t)y^{(n-1)} + \cdots + a_{n-1}(t)y^{(1)} + a_n(t)y = g(t)$$

 $a_i(t), g(t)$  are functions of the independent variable t.

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